The Ninth Annual
Autonomous Snowplow
Competition

Rulebook

Revision 2019.2

Sidewalk Labs
Toronto, Canada
24-26 January 2019
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1 Introduction

The Institute of Navigation (ION) and its Satellite Division are pleased to announce the Ninth Annual Autonomous Snowplow Competition (ASC). This competition is operated and managed by the ION North Star Section based in Minneapolis, MN.


The objective of the ASC is for teams to design an unmanned snowplow vehicle that will autonomously remove snow from pre-defined paths. The competition invites and challenges teams in the area of high-performance autonomous vehicle guidance, navigation, and control. The competition is also designed to encourage student interest in the areas of science, technology, engineering, and mathematics.

ASC teams are required to build snowplow vehicles to autonomously remove snow from two snowfields within a set amount of time. The two snowfields have straight ‘I’-shapes. The first snowfield has a single ‘I’-shaped path. The second snowfield has two parallel (side-by-side), or double, ‘I’-shaped paths. Teams can implement navigation-aiding systems surrounding the snowfields to aid the snowplow vehicle’s navigation systems; however, there can be no direct human control of the vehicle during the plowing operation.

The Ninth Annual Autonomous Snowplow Competition will take place during a competition week held in collaboration with Sidewalk Labs during January 2019 in Toronto, Canada. The competition week will be composed of the following events:

- Thursday, 24 January 2019: Teams will present their final snowplow vehicle designs to the general public.
- Friday, 25 January 2019: Teams will qualify and demonstrate the operability and safety of their snowplow vehicles.
- Saturday, 26 January 2019: Teams will compete on the single straight ‘I’-shaped snowfield, and the double straight ‘I’-shaped snowfield.
Teams will be judged throughout the competition week activities. In the design phase of the competition, teams will have the chance to present their snowplow vehicle concepts and hone their presentation skills during regular Vehicle Status Reviews (VSRs). These VSRs will be held in November and December 2018 and January 2019. During the competition week, teams have the opportunity to display and demonstrate their snowplow vehicle design through public presentations, and will be judged on their vehicle’s performance of removing snow from the two competition snowfields.

The Thursday evening Student Poster Session and Reception event will be held at:

Sidewalk Toronto
307 Lake Shore Blvd. East
Toronto, Ontario M5A 1C1
Canada

The event will include a social hour, where ASC teams will have an opportunity to meet members of the other ASC teams, the ASC Officials, ASC Judges, the ION Executive Committee, Sidewalk Labs personnel, and members of the public. Easels will be provided for teams so they can present a poster or similar display of their snowplow vehicle design during this reception. ASC teams should plan to have their vehicles on display at this event and plan to be available to answer questions about their vehicles by members of ASC Committee, ASC Judges, Sidewalk Labs, and the general public.

A Final Qualification Review (FQR) Vehicle Demonstration and Safety Inspection will be conducted on Friday of the competition week. This FQR demonstration and inspection is conducted prior to the dynamic competition to ensure the snowplow vehicles satisfy the ASC design, operability, and safety requirements defined within this rulebook.

The Friday snowplow vehicle FQR and the Saturday dynamic competitions will be held at the snowplow competition field located at:

Sidewalk Toronto
307 Lake Shore Blvd. East
Toronto, Ontario M5A 1C1
Canada

The ASC will award prizes to teams within the competition. Teams that accumulate the most number of points during the competition week will be awarded cash prizes and trophies. The best student presentation during the Student Poster Session and Reception event during the competition week will be awarded the Golden Shovel Award. The team demonstrating the most enthusiasm and spirit throughout the competition will be awarded the Dr. Nattu Golden Smile Award.

In addition to the competition prizes, student teams may apply for grants through the ION to support their travel costs to the competition week.
2 General Information

2.1 Team Rules

2.1.1 Team Composition

The ASC welcomes teams comprised of high school, college, university undergraduate and graduate students, and members of the general public. All team members must be 18 years or older.

All ASC teams, including teams comprised of members of the general public, must have at least one student member. The student members of ASC teams are entirely responsible for performing the Student Poster Presentations. Teams comprised primarily of high school, college, or university students should have a faculty advisor. Student teams are encouraged to invite students from all technical or engineering programs, as well as students from business programs, to design and promote the snowplow vehicle, solicit funding, and perform program management responsibilities.

Colleges, universities, and institutions are welcome to enter more than one team into the ASC. Multiple teams may compete using the same snowplow vehicle. However, no team members may be in common between any competition team. Furthermore, each team’s navigation aiding system must be designed independently and these unique designs must be clearly evident to the ASC Judges. Multiple teams from the same institution are required to independently prove their designs are unique. If multiple vehicles are entered from the same institution, then a different team must design each snowplow vehicle. Faculty advisors are allowed to advise more than one team. Each ASC team must submit a separate ASC Application Form accompanied with the full team entry fee.

2.1.2 Team Sponsorship

ASC teams are responsible for acquiring their own funding to design and build their snowplow vehicles. The competition organizers will work to gain sponsorship to provide partial funding for the competition week through travel grants; however, all ASC teams are responsible for their own travel to the competition venue. Therefore, ASC teams are encouraged to solicit sponsors to fund their team entry. Documentation from the ASC website can be used to provide potential sponsors with information about the ASC.

Sponsors are allowed to provide funding or hardware for teams. Furthermore, teams can place sponsor logos on their snowplow vehicle or navigation aiding sources, and can also place sponsor banners at the competition week’s events.
2.1.3 Competition Application Procedures

Teams are required to enter the ASC by submitting a completed ASC Application Form. The ASC Application Form can be downloaded from the ASC website. Each ASC team entry must be documented by a separate ASC Application Form.

Each ASC Application Form must be accompanied by a non-refundable registration and entry fee of $100.00 made payable to: Institute of Navigation. For credit card payments, please contact the Institute of Navigation National Office at the phone number below. This entry fee includes a complementary one-year ION professional membership for the team’s advisor.

The ASC Application Form must contain an Indemnification Agreement executed by an individual from the team’s sponsoring institution who has authority to bind the institution for which he or she signs. Additionally, each team is required to provide a Certificate of Insurance at the time the Application Form is submitted. This Certificate of Insurance may be supplied by the team’s sponsoring institution or by a commercial insurance company, and it must show commercial general liability coverage in an amount not less than $1 million (USD).

The completed ASC Application Form, the Application Fee, and the Certificate of Insurance are to be submitted to the ION National Office, as noted on the ASC Application Form, and must be received/postmarked no later than 21 September 2018.

This deadline is provided to support schools that start their semester in early September.

Please note that we highly recommend that all ASC teams apply as early as possible, and begin the design and development of their snowplow vehicles long before this deadline.

Each ASC team must inform both the ION National Office and the ION North Star Section of its intention to compete in the ASC. Mail, fax, or email a copy of the completed, signed ASC Application Form and Certificate of Insurance to both of the following:

**Autonomous Snowplow Competition**
The Institute of Navigation
Lisa Beaty, Executive Director
8551 Rixlew Lane, Ste. 360
Manassas, VA 20109-3701
lbeaty@ion.org
Phone: 703-366-2723
Fax: 703-366-2724

**Dr. Suneel I. Sheikh**
North Star Section Outreach Chair
ASTER Labs, Inc.
155 East Owasso Lane
Shoreview, MN 55126-3034
sheikh@asterlabs.com
Phone: 651-484-2084
Fax: 651-484-2085
2.2 Website

The main source for information about the ASC is via the competition website, which includes contact information for communication with the ASC Officials and Judges:

www.autosnowplow.com

This website contains general information about the competition, competition documentation, past event information, current sponsors and sponsorship information, and competition contact information.

The ASC documentation available on the website includes the ASC Application Form, the ASC Rulebook, and ASC flyers. Outlines of the Student Poster Presentation format are available on the website, and will also be sent directly to ASC teams during the competition.

2.3 Timeline

The timeline for the ASC is provided in Table 1. The timeline is designed to give teams time to design and build their snowplow vehicles culminating with the competition week held in collaboration with Sidewalk Labs on 24-26 January 2019.

ASC teams are encouraged to explore and enjoy the city of Toronto, Ontario, Canada as much as time permits during the competition week.

Table 1. Competition Timeline.*

<table>
<thead>
<tr>
<th>Event</th>
<th>Date</th>
</tr>
</thead>
<tbody>
<tr>
<td>Entry Application Deadline</td>
<td>21 September 2018</td>
</tr>
<tr>
<td>Kickoff Meeting Individually With Teams</td>
<td>October 2018</td>
</tr>
<tr>
<td>Interim Status Meeting with Teams</td>
<td>15 November 2018, 3:00 PM</td>
</tr>
<tr>
<td>Interim Status Meeting with Teams</td>
<td>7 December 2018, 3:00 PM</td>
</tr>
<tr>
<td>Final Status Meeting with Teams</td>
<td>17 January 2019, 2:30 PM</td>
</tr>
<tr>
<td>Student Poster Session and Reception</td>
<td>24 January 2019, 6:00 PM</td>
</tr>
<tr>
<td>FQR Vehicle Demonstration and Safety Inspection</td>
<td>25 January 2019, 11:00 AM</td>
</tr>
<tr>
<td>Single Straight 'I'-Shaped Snow Path Competition</td>
<td>26 January 2019, 7:00 AM</td>
</tr>
<tr>
<td>Collaborative Operational Challenge Demonstration</td>
<td>26 January 2019, 11:00 AM</td>
</tr>
<tr>
<td>Double Straight 'I'-Shaped Snow Path Competition</td>
<td>26 January 2019, 1:00 PM</td>
</tr>
<tr>
<td>Competition Awards Ceremony</td>
<td>26 January 2019, 5:00 PM</td>
</tr>
</tbody>
</table>

*Note: All times listed are U.S. Central Time Zone

**Note: Sidewalk Toronto is located in the U.S. Eastern Time Zone
2.4 Document Revision History

The ASC Rulebook is provided to teams as soon as the competition has been defined. ASC Officials reserve the right to update the Rulebook during the competition.

Revisions to the rules will be provided based upon competitor feedback and contest limitations. Teams are encouraged to monitor the ASC website for the latest competition information and versions of the ASC Rulebook.

ASC Rulebook Versions

- Version 2019.1
  - Initial Draft released to competitors
  - New Sponsors list
  - Collaborative Operational Challenge expanded
- Version 2019.2
  - Fixed year dates in Timeline
  - Updated Sponsors list
  - Revised scoring algorithm
3 Autonomous Snowplow Contest

3.1 Overview

The objectives of the ASC are to design and operate an autonomous, unmanned snowplow vehicle to quickly and accurately clear snow from two rectangular snowfields using the art and science of guidance, navigation, and control. ASC teams are judged based upon their scores earned throughout the dynamic plowing competition tournaments.

3.2 Rules and Regulations

3.2.1 Snowplow Vehicle Design

The ASC is designed to challenge teams in the areas of high-performance autonomous vehicle guidance, navigation, and control. In addition to these challenges, the ASC also provides teams with interaction and feedback from industry experts throughout the entire design process from initial concept design through to the dynamic snowplow competition.

The ASC welcomes all innovative designs for a snowplow vehicle. However, as in any industry design of a concept vehicle, the vehicle must satisfy certain requirements for design, cost, and marketing purposes. Therefore, the ASC Officials have imposed several constraints on the snowplow vehicle design that would exist for vehicles used to remove snow from sidewalks or driveways, as well as to satisfy safety and practicality constraints:

1) Snowplow vehicles shall be autonomous and unmanned, and they shall not be remotely controlled during the competition. During the dynamic snowplow competitions, the snowplow vehicle may be moved from the snowplow staging area to the competition snowfields with human assistance. However, the snowplow vehicle must not receive human assistance while it is removing snow from a snowfield. Any team whose snowplow vehicle receives human assistance while removing snow from a snowfield will be disqualified from that portion of the competition and receive zero points for that portion of the competition. Remotely controlled includes, but is not limited to: commands to modify or reset the snowplow vehicle's computers, commands to reinitialize the snowplow vehicle, commands to adjust a plowing route, etc.

2) For safety reasons, each snowplow vehicle has a speed limit of 2 m/s that shall be strictly enforced.
3) The snowplow vehicle must be equipped with an Emergency Stop System (ESS), which consists of both a physical power-off switch and a wireless remote power-off switch that independently removes power from the vehicle’s drive system. The physical, or manual, power-off switch must be easily identifiable and easily accessible to a person walking behind the snowplow vehicle. This switch must be located on the top surface of the vehicle and there shall not be any other protruding objects within a 30 cm radius of the switch. This emergency stop switch shall be red in color and have a diameter of at least 40 mm. The wireless remote power-off switch shall remove power from the vehicle’s drive system when a signal from the wireless control unit switch is received. The wireless remote power-off switch must have a minimum range of 50 m. The snowplow vehicle shall cease operation and come to a complete stop within 3 meters upon activation of either the physical or wireless remote power-off switch. The ESS shall not have a single point of failure, such that no single failure in the ESS or the vehicle shall inhibit the ESS from removing power from the vehicle’s drive system. It is recommended that the ESS not process data through or require computer operation for the emergency stop. The ESS power cut-off capabilities of the snowplow vehicle must be demonstrated at the competition FQR Vehicle Demonstration and Safety Inspection. Snowplow vehicles that are determined to be unsafe or fail to meet the ESS requirements, as specified herein and as determined by the ASC Judges, shall not be allowed to participate in the competition.

4) The snowplow vehicle and any of its attachments must not exceed 2 m in any dimension.

5) The plowing action may be completed using a fixed plow blade and/or rotating brushes. Rotating brushes must operate such that no hard object (ice, pebble, etc.) can be ejected at a speed that will harm a person. No snowblowing – using an auger to ingest snow and chute to eject snow – implements are allowed.

6) The ASC will take place on a downtown city parking lot or street that has a ground surface made of concrete pavers and/or asphalt. Sidewalk Labs has added the following constraints on the design of the snowplow vehicle tires to preserve the concrete paver surface: the tires shall not be augmented with metal rivets, spikes, or chains to gain traction. Knobby, rubber winter tires are allowed. Other plastic or rubber augmentations to the tires are allowed. For example, metal wire coated with plastic or vinyl insulation may be wrapped around tires for traction. However, if the insulation jacket becomes damaged exposing the underlying wire, then the coated wire must be replaced prior to operating on the snowfield.

7) The snowplow vehicle must be self-powered and contain no power source external to the vehicle. Power shall either be by combustible fuel, batteries, or both. Other power sources must be cleared with the ASC Officials prior to the competition.

8) The plowing action shall be accomplished through direct contact with the ground surface.

9) The snowplow vehicle must be equipped with an electrical ground.
3.2.2 Final Qualification Review Vehicle Demonstration and Safety Inspection

The Final Qualification Review (FQR) Vehicle Demonstration and Safety Inspection is an opportunity for ASC teams to display their snowplow vehicles to the ASC Judges and demonstrate that their snowplow vehicles satisfy the design requirements and constraints. ASC teams must demonstrate the following at the FQR:

- Their snowplow vehicle and navigation-aiding sources satisfy the ASC design constraints including vehicle dimensions, power, and electrical ground.
- The operability of both the physical power-off switch and remote power-off switch of the ESS.
- Their snowplow vehicle satisfies the ASC speed limit requirements by displaying their speed limit software, speed control hardware, and by running their snowplow vehicle at its maximum speed.
- Their snowplow vehicle can operate autonomously.

ASC teams are allowed to modify their snowplow vehicles or navigation-aiding sources should they fail their initial FQR Vehicle Demonstration and Safety Inspection and resubmit their vehicle or aiding sources for review. Any physical modifications to the vehicle require a new review to verify that vehicle safety and other requirements are met. Once a snowplow vehicle and navigation-aiding sources have passed the FQR Vehicle Demonstration and Safety Inspection, ASC teams are not allowed to modify their vehicle’s speed limit software or speed control hardware. ASC teams are allowed to modify their guidance, navigation, and control software any time during the competition subject to competition time limits.

The FQR Vehicle Demonstration and Safety Inspection will take place on Friday of the competition week at the competition field in downtown Toronto. The FQR Vehicle Demonstration and Safety Inspection will begin as noted in Table 1 with a schedule published by the ASC Officials in advance of the competition week. Each team will be given an initial 15 minute time period during which the ASC Safety Judges will ensure that the snowplow vehicle and navigation-aiding sources satisfy the competition rules. If a team initially does not pass the FQR Vehicle Demonstration and Safety Inspection, then the team will be given as many inspections as needed until 6:00 pm on Friday evening to satisfy the ASC Safety Judges that the snowplow vehicle and navigation-aiding sources satisfy the competition rules. The decisions of the ASC Judges are final.

During the FQR Vehicle Demonstration and Safety Inspection period, all ASC teams will be given the opportunity to view the competition snowfields and test their snowplow vehicles on a practice area at the competition site. ASC teams may not test their vehicles within the dynamic competition area during the FQR Vehicle Demonstration and Safety Inspection period.
3.2.3 Competition Plowing

1) The snowplow vehicles will be required to start autonomous operation in the Vehicle Starting Zone (Garage) and plow within the Snow Path areas.

2) The timer to begin each plowing run will be started from zero when the snowplow vehicle is within the Vehicle Starting Zone and the ASC teams and ASC Safety Officials declare they are ready.

3) The Snow Path has buffer zones extending from their outer boundaries called the Vehicle Starting, Maneuvering, and Plowed Snow Zones. A snowplow vehicle must stay within these boundaries at all times once it begins to clear snow from the Snow Path.

4) If any part of the snowplow vehicle extends outside the prescribed Vehicle Starting, Maneuvering, or Plowed Snow Zones, the ESS power-off switch shall be activated, a boundary infraction will be declared, and the vehicle must be moved back into the nearest plowed square-meter section of the Snow Path before a plowing run may be resumed. The penalty of time delay when repositioning the snowplow vehicle will be assessed for this boundary infraction as detailed in the scoring section below.

5) Teams are permitted restarts during each competition run. The snowplow vehicle must be repositioned back into the Vehicle Starting Zone for a restart. If an ASC team chooses to restart, then the accumulated time of repositioning the snowplow vehicle will be assessed as detailed in the scoring section below.

6) Teams have a maximum of 20 minutes to clear snow from the Snow Path. The 20 minutes refers to the total plowing time allowed, and it includes the initial competition plowing run, and possible plowing run restarts.

7) Team members, snowplow vehicles, or navigation-aiding sources may not touch any snow in the Snow Path prior to beginning a competition plowing run.

8) The snowplow vehicle should be designed to operate in any weather condition. In the event of severe weather, the competition may be postponed. The decision to postpone an event shall be made by the ASC Officials.

9) The snowplow vehicle may be equipped with eye-safe (Class 1) lasers. However, the lasers must be affixed to the snowplow vehicle and pointed towards the ground, with an angle at or below the local horizontal plane of the laser device. If lasers are used on the snowplow vehicle, then the laser harness and mounting to the vehicle must be displayed during the FQR Vehicle Demonstration and Safety Inspection. If requested by ASC Officials, then the team is obligated to provide proof (sensor’s certification sticker is sufficient) that the laser complies with Class 1 regulations.
10) Teams may place multiple navigation-aiding sources surrounding the Snow Path, but the sources must remain within the Maneuvering Zones and/or Plowed Snow Zones. These navigation-aiding sources must be stationary following their placement within the competition area.

11) Teams that choose to place navigation-aiding sources surrounding the Snow Path may place all aiding sources prior to the start of their plowing run. Once the timer starts for the team’s plowing run, all team members, except one with wireless remote power-off switch, must remain in the Team and Navigation Aids Starting Zone. The placement of these aiding sources and any associated field surveys must be completed prior to the 20-minute allotted competition time.

12) A secondary navigation-aiding source zone will be provided to teams for placement of remote navigation aids requiring longer set up time (e.g. differential GPS stations). This secondary navigation-aiding source zone will be located on the competition event site, but not directly within the snowfield boundaries. Teams cannot be assured of direct line of sight between this zone and a competition field, as this zone may be blocked by competition structures, competition volunteers, other competitors, or other aids. Set up for these remote navigation-aiding sources will not count towards the 20-minute allotted competition time.

13) The navigation-aiding sources may be actively emitting signals (e.g. radio, ultrasonic). If active, these navigation-aiding sources must be self-powered.

14) The ESS must be operational and active anytime the snowplow vehicle is in operation at or near the site of the competition.

15) Neither the snowplow vehicle nor the navigation-aiding sources may expel any fluids or objects of any kind within the snowfield competition boundaries. This ensures the road surface and snowfield conditions will remain identical for all teams. Snowplow vehicle plow blades may not be heated, as this will cause plow snow to melt and act as an expelled liquid.

16) At the end of a competition plowing run, the snowplow vehicle must autonomously return and park within the Vehicle Starting Zone (Garage) on the snowfield. A time penalty will be assessed if no portion of the snowplow vehicle is parked within this zone. The snowplow vehicle must remain within the snowfield boundaries as it returns to the Vehicle Starting Zone (Garage).

17) No team member, snowplow vehicle, or navigation-aiding source is allowed on the competition field after hours of operation, as posted by ASC Officials. This limitation is for safety and insurance reasons.
3.2.4 Competition Procedures

Prior to a competition run, ASC team members may move their snowplow vehicle directly into the Vehicle Starting Zone on the competition snowfield, with the assistance of ASC Safety Officials. Teams can use the vehicle’s power supply to maneuver their vehicle into the Vehicle Starting Zone. The vehicle can be turned off (unpowered) until the competition run officially begins, unless necessary for vehicle operation (e.g. provide heat to systems, keep navigation aids active). If the vehicle is turned on, then teams must have their ESS system active to ensure the vehicle can be turned off immediately by an ASC Safety Official as necessary. Teams should notify ASC Safety Officials of their intent of powered operation prior to starting a competition run.

Prior to their respective competition run, ASC team members can locate their navigation-aiding sources within the Maneuvering Zones and/or the Plowed Snow Zones as required by the team’s design. ASC team members must then move into the Team and Navigation Aids Starting Zone and remain there until their run begins.

Each ASC team is given a total of 20 minutes for their entire snowfield competition run.

An ASC team’s run commences upon notification by the ASC Marshal. Snowplow vehicles can then be powered on (started). Teams may initiate plowing operation at any time during their allotted 20 minutes to enable their snowplow vehicle to clear snow from the Snow Path. An ASC team’s run concludes when any part of the vehicle enters the Vehicle Starting Zone (Garage). If a vehicle fails to return to the garage at the end of the run, the run may conclude when a team member indicates to the ASC Marshal that their run is finished.

Once an ASC team’s 20 minute plowing window is completed, the team must take their snowplow vehicle and navigation-aiding sources back to the staging area. The ASC Judges will then assess the performance of the snowplow vehicle on the Snow Path, and the ASC Snow Pit Crew will prepare the Snow Path for the next ASC team.

The ASC Marshal will oversee the snowplow vehicle competition schedule to ensure that the ASC events begin and end as scheduled.

Before an ASC team turns on their snowplow vehicle within the competition snowfield, the team must show the ASC Safety Official the operation of the remote power-off switch. A single member of the ASC team will then maintain control and operation of the remote power-off switch. Along with an ASC Safety Official, this single member will remain outside but adjacent to the snowfield boundaries while a team’s snowplow vehicle is clearing snow from a Snow Path to operate the power-off switch or declare a restart. After a boundary zone infraction, a power shut down, or a declared restart, the remaining ASC team members are allowed within the snowfield boundaries to assist with repositioning the vehicle to either the nearest plowed square-meter section of the Snow Path or back to the Vehicle Starting Zone. ASC team members must minimize the amount of uncleared snow disturbed while repositioning their vehicle at the direction of the ASC Marshal. The ASC Safety Officials have the authority to engage either the physical power-off switch or remote power-off switch if the snowplow vehicle should travel outside the Vehicle Starting, Maneuvering, or Plowed Snow Zones. The decisions of the ASC Marshal and Safety Officials are final.
## 3.3 Snowfield Specification

The ASC will take place in downtown Toronto, Ontario, Canada. The snowfield competition location is 307 Lake Shore Blvd East. In addition to this location’s parking lot, an adjacent roadway of Small Street will be closed to traffic from Friday through Saturday of the competition week to facilitate the FQR Vehicle Demonstration and Safety Inspection and the dynamic plowing competitions.

Sidewalk Toronto has a concrete paver surface in their parking lot. The adjacent roadway, Small Street, has an asphalt surface. ASC Officials will make every attempt to ensure that the snowfield paths are evenly constructed and fair for all ASC teams. This venue is located in an urban environment with tall city buildings surrounding the snowfields.

The ASC has two competition snowfields, which include a **single straight ‘I’-shaped** path, shown in Figure 1, and a **double straight ‘I’-shaped** path, shown in Figure 2. The dimensions of the two Snow Paths as well as the Vehicle Starting, Team and Navigation Aids Starting, Maneuvering, and Plowed Snow Zones are provided in these figures.

For both Snow Paths, the snow depth will vary between **5.0 to 15.0 cm**. The decision of the snow depth variation is strictly up to the ASC Marshal’s and Judge’s discretion and will be implemented as part of the competition day setup. ASC teams should anticipate this variation during their snowplow vehicle design and development. The ASC Officials will make every effort to ensure that the snowfield paths have the same total quantity of snow for each ASC team, but the snowfield path depth and the snow consistency cannot be guaranteed to be exactly the same for each ASC team.

The external boundaries of the Vehicle Starting, Maneuvering, and Plowed Snow Zones will be marked with PVC pipe, wood strips, metal bars, web strapping, or chalk markings on paver or asphalt pavement. These boundaries and zone markings will be obvious to ASC team members, Officials, and the viewing public.
Figure 1. Single straight ‘I’-shaped competition path snowfield diagram.
Figure 2. Double straight ‘I’-shaped competition path snowfield diagram.
3.3.1 Simulated Posts

Many house driveways have adjacent trees, and city sidewalks typically have parking meters. Some of these objects are located near but do not interfere with a snowplow vehicle when plowing a path or driveway. Other objects that are located on a sidewalk or driveway will interfere with the snowplow vehicle’s path, and must be avoided by a snowplow vehicle.

To simulate fixed objects within the competition snowfield, two fixed posts, approximately 1.5 m high by 0.2 m wide, will be placed within the boundaries of the competition field during both dynamic competition runs. These fixed posts will be included within both the single straight ‘I’-shaped and the double straight ‘I’-shaped snowfields. Random locations for these posts for each ASC team run will be chosen by the ASC Marshal and Judges. The placement of these fixed posts will occur immediately prior to a team’s 20-minute competition run.

For the single straight ‘I’-shaped field, both first fixed posts will be placed outside of the Snow Path.

For the double straight ‘I’-shaped field, one of the fixed posts will be placed outside of the Snow Path, and the second fixed post will be placed directly within the Snow Path. The first fixed post will be placed within the Maneuvering or Plowed Snow Zones outside of the Snow Path. The 1-m² section in which the second fixed post is placed will not have any snow, so it does not need to be plowed by the snowplow vehicle.

The fixed posts are considered part of the competition snowfield and no objects, such as navigation aids, may be physically attached to these posts by the ASC teams during their plowing run.

Snowplow vehicles must avoid each fixed post. ASC teams will receive a bonus to their time score if any part of their snowplow vehicle avoids hitting, moving, or toppling over the post located directly within the Snow Path during their run or if the post is not moved from its original location in the snowfield by any other action, including the action of plowed snow being pushed by the snowplow vehicle. This bonus will adjust the team’s overall competition run time.

Moved or fallen snow from the snowplow vehicle is allowed to touch either post, and no points for hitting a post will be deducted if only snow (and no part of the vehicle) touches or remains on the post and does not move the post from its original location on the snowfield.
3.3.2 Moving Obstacle

A critical function of autonomous vehicles is to detect and avoid any obstacles within their path. This especially includes those obstacles that are moving and crossing the intended path of the vehicle. These obstacles could indicate a pet, child, adult, other vehicle, or another important item has moved into the snowfield and in the way of the snowplow vehicle. The purpose of this obstacle in the ASC is to encourage competitors to design a snowplow vehicle system that will prevent any part of the vehicle from impacting a moving obstacle.

FOR THIS COMPETITION YEAR ONLY, THERE WILL BE NO MOVING OBSTACLE AS PART OF THE EVENT.

For competitor’s reference only, in previous events to simulate moving obstacles within the competition snowfield, a single flat object approximately **0.5 m high by 0.5 m wide by 0.03 m thick**, would enter the boundaries of the competition field during the dynamic competition runs. This moving obstacle occurred in both the past single straight 'I'-shaped and the triple straight 'I'-shaped snowfields. The moving obstacle event would occur at a random time during each of the ASC team’s 20 minute plowing run, at a time chosen by the ASC Marshal and Judges.

The moving obstacle would enter and stop directly within the Snow Path. The moving obstacle would travel in a straight line perpendicularly across the field (+/- 90° with respect to the long axis of each Snow Path). The obstacle would move at a maximum of 3 m/s. The Moving Obstacle would come to rest, at least 0.5 m above the snow within the Snow Path. The moving obstacle’s motion would be coordinated such that when entering the competition snowfield it will not impact any part of the snowplow vehicle before coming to rest along the Snow Path.

In past events, snowplow vehicles were required to avoid the moving obstacle by coming to a complete stop once the obstacle is detected by the vehicle. All snowplow vehicle wheels and/or tracks were required to stop turning, and the vehicle would not have forward, backward, or rotating motion, which will indicate a complete stop. Once the snowplow vehicle came to a complete stop, the moving obstacle would be immediately removed from the competition snowfield, and the snowplow vehicle could resume its snow removal from the Snow Path.

In past events, once the Moving Obstacle entered the snowfield and became visible to the snowplow vehicle, ASC teams were assessed a penalty if the snowplow vehicle did not come to a complete stop or if any part of the snowplow vehicle hit, moved, or toppled over the obstacle during their plowing run. This penalty would reduce the ASC team’s overall score.
3.3.3 Collaborative Operational Challenge

The Collaborative Operational Challenge (COC) is an independent event, for the purpose of demonstration. The objective of this challenge is for a snowplow vehicle to autonomously operate in tandem with other snowplow vehicles on the same snowfield to remove as much snow as possible in the shortest period of time. This collaborative task must be done safely and without collision between snowplow vehicles.

As there is a certain risk to any team’s snowplow vehicle, the COC is considered an optional demonstration event within the overall ASC. Teams can elect to enter, participate, and compete in the COC, or elect to not participate in the COC without penalty. Additional awards will be provided to COC participants and winners outside of the ASC award structure. COC participation will not in any way affect a team’s standing or performance within the overall ASC.

The COC will be conducted on one or two straight ‘S’-shaped snowfields. This straight ‘S’-shaped snowfield configuration is shown in the diagram of FIGURE 3, which illustrates the 3 m by 9 m rectangular area of the snowfield.

Each COC event will involve a 20-minute demonstration. Two snowplow vehicles will be initially placed in their respective starting garages, either together or at opposite ends of the straight ‘S’-shaped snowfields. At the beginning of the run, each snowplow vehicle will commence plowing the sections directly in front of the vehicle, with the objective of plowing these sections and returning to the starting garage as fast as possible. Snowplow vehicle may collaborate by following one another, taking separate routes, or combinations of these schemes to clear the Snow Path. Any snowplow vehicle requiring external navigation aids may set these up prior to the 20-minute COC demonstration run.

During the COC demonstration, snowplow vehicles must not collide with each other. If either snowplow vehicle detects a threat of a collision, it must take evasive action to avoid colliding with the other vehicle.
Figure 3. Single straight ‘S’-shaped demonstration path snowfield diagram.
3.4 Competition Scoring

ASC teams will primarily compete in a modified tournament-style competition. Each snowfield will have a separate tournament. The ASC events and scoring methods are provided in this section.

Table 2. Overall Competition Events.

<table>
<thead>
<tr>
<th>Event</th>
</tr>
</thead>
<tbody>
<tr>
<td>Final Student Poster Presentation</td>
</tr>
<tr>
<td>Snowplow Competition: Single 'I'-Shaped Snow Path</td>
</tr>
<tr>
<td>Snowplow Competition: Double 'I'-Shaped Snow Path</td>
</tr>
</tbody>
</table>

The scores awarded by ASC Judges in all phases of the snowplow competition are final. Competitors must be aware that all decisions by the ASC Judges are final.

3.4.1 Technical Presentation Scoring

ASC teams are required to present their snowplow vehicle designs in poster presentations at the Student Poster Session and Reception. Recommendations for the Student Poster presentation format can be downloaded from the ASC website. The exact procedure for document submission will be provided to the ASC teams well in advance of the submission deadlines.

The Student Poster Presentations of the ASC teams will be scheduled for Thursday evening of the competition week, as shown in the ASC Timeline in Table 1. The Student Posters are due at the time of the presentation event. Teams are strongly encouraged to produce original presentation work each year, as ASC Judges will reduce scores for non-original work. The Student Poster Presentations must be delivered by student members of the ASC team.

The Student Poster Session and Reception will be attended by the ASC Officials and Judges and are open to other ASC teams, as well as the general public. Teams should bring posters or displays describing their snowplow vehicle designs and operation for show prior to the presentations, as ASC Judges and the audience will review these posters when meeting the teams during the social hour. This team and Judge interaction can often improve a team’s score.

The Student Poster Presentations scores will be based on the following scoring system:

Table 3. Presentation Scoring System

<table>
<thead>
<tr>
<th>Category</th>
<th>Points</th>
</tr>
</thead>
<tbody>
<tr>
<td>Technical Assessment and Quality of Presentation Poster</td>
<td>80</td>
</tr>
<tr>
<td>Ability to Engage Audience and Answer Questions</td>
<td>20</td>
</tr>
<tr>
<td><strong>TOTAL Points</strong></td>
<td><strong>100</strong></td>
</tr>
</tbody>
</table>
3.4.2 Plowing Competition Scoring

During the dynamic snowplow competition, ASC teams will compete using their snowplow vehicles to clear snow from the snowfield paths. Snow is considered cleared from a snowfield path if the vehicle plows the snow out of the Snow Path into the Plowed Snow Zones. An ASC team’s vehicle performance in clearing snow from a Snow Path will be evaluated and assessed by a distinguished panel of ASC Judges, who will determine the percentage of the path cleared of snow within each 1-m\(^2\) section of the snowfield path. A minimum of 50% of the Snow Path must be cleared for a team to be qualified in each competition run. Clearing less than 100% of the Snow Path will result in a time penalty.

ASC teams are primarily scored by the amount of time their snowplow vehicles take during a 20-minute competition run to clear the Snow Path. Time of each competition run is recorded to the nearest second, and will start at the Judge’s whistle, include any time for restarts or boundary infractions, and end once the snowplow vehicle enters the garage (as verified by both Judges and the competitor’s team members) or upon verbal declaration by a team member to the ASC Marshal that their run is concluded.

A tournament style will be used to determine the overall winner. A tournament bracket that displays the breakdown of each competition event is provided in Figure 4. In each bracket, the team with the overall lowest time to complete their run will be declared the winner. The two teams with the lowest times in comparison to all other competitors will advance to the final round of the tournament.

ASC teams have a continuous overall competition run time, even if their snowplow vehicle requires a restart after their vehicle begins to plow snow or if any part of their vehicle extends out of the Vehicle Starting, Maneuvering, or Plowed Snow Zones. ASC teams will accumulate competition run time for each snowplow vehicle restart and for any snowfield Vehicle Starting, Maneuvering, or Plowed Snow Zone boundary infraction by their vehicle.

It is important that plowed snow be moved to areas that do not impede foot or vehicle traffic. Thus, ASC teams are penalized for allowing any plowed snow to remain in the wrong zones along the competition snowfield. Snow must be plowed out of the Snow Path and moved into the Plowed Snow Zones, as marked on the snowfield diagrams. ASC teams may use the Maneuvering and Vehicle Starting Zones to maneuver their vehicle or move snow between zones. If more than 50% of the snow plowed from the Snow Path remains in either the Maneuvering Zones or Vehicle Starting Zones at the end of their run, then ASC teams are assessed a time penalty based upon overall competition run time.

Snowplow vehicles are required to park inside the Vehicle Starting Zone (Garage) at the end of their run. If any portion or all of the snowplow vehicle crosses the zone lines, the vehicle will be considered parked within the garage. Teams will be assessed a time penalty based upon field size if the snowplow vehicle fails to autonomously park inside the Vehicle Starting Zone at the end of the competition run. A team may not declare a restart to gain the advantage of locating in the Vehicle Starting Zone at the end of their plowing run.
Snowplow vehicles should maneuver to avoid both posts located within the competition snowfield. No part of the snowplow vehicle should strike a post during a run. Snow may fall up against a post without loss of points for hitting the post. However, any snow remaining on the Snow Path will reduce the assessment of plowed snow, and snow on the post will be considered as snow remaining on the Snow Path. If any part of a snowplow vehicle avoids striking or moving a fixed points post in the Snow Path, then a time bonus based upon field size will be added to the score, that will reduce a competitor's competition run time.

**Autonomous Snowplow Competition**

**Modified Tournament Bracket**

**Round 1 – Sidewalk Pavers**
- Team: ____________________
- Time: ____________________

**Round 2 – Small Street**
- Team: ____________________
- Time: ____________________
- Team: ____________________
- Time: ____________________

**Final Round – Sidewalk Pavers**
- Team: ____________________
- Time: ____________________
- Team: ____________________
- Time: ____________________

- Two lowest timed teams overall advance to final round.

**Round 4 – Small Street**
- Team: ____________________
- Time: ____________________
- Team: ____________________
- Time: ____________________

**Figure 4. ASC modified tournament bracket.**
For each snowfield path, the competition run time awarded for the snow clearing performance will be scored using the following formula:

\[ T_{SC} = t_{SC} \left[ \left( 1.10^{(1-D)} \right) \left( 100/C_P \right) \right] + (1 - G) P_G - (M_1) B_M \]

where,

- \( T_{SC} \) = time points for snow clearing
- \( t_{SC} \) = recorded time (nearest second) for snowclearing until declared return to garage (or end run)
- \( D \) = drift snow remaining (= 1 if > 50% plowed snow in Plowed Snow Zones, otherwise = 0)
- \( C_P \) = percentage of snow path cleared (must be greater than 50% to be qualified)
- \( G \) = garage parking (= 1 if successful, and = 0 if unsuccessful)
- \( P_G \) = penalty for not parking in garage (= 20 s for Single "I", and 40 s for Double "I")
- \( M_1 \) = simulated fixed snow path post (= 1 if avoided, and = 0 if struck)
- \( B_M \) = bonus for avoiding all obstacles (= 7.5 s for Single "I", and 15 s for Double "I")
3.5 Awards and Prizes

The ASC will award prizes to competition teams in multiple categories. The amounts of the monetary awards are subject to change depending on the availability of sponsorship funds. The cash amount for each prize will be posted on the ASC website:

www.autosnowplow.com

The ASC will award the prestigious Golden Shovel trophy and cash prize to the best Student Poster Presentation. ASC teams will be considered for the Golden Shovel award based on the average of the total points accumulated from the ASC Judges after the review of the Student Posters. The ASC team with the highest accumulated score in this event will win the award.

The ASC will award the Dr. Nattu Golden Smile trophy and cash prize for the team exhibiting the best sportspersonship throughout the competition. The ASC Committee will select a team for this award based upon team’s participation, enthusiasm, and support of their own and other competitor’s team. This award is named in honour of Dr. Narasimhamurthi Natarajan (often called “Nattu” for short) from the University of Michigan, Dearborn, who led over ten competition teams at the ASC, including three teams in the 2014 ASC year, and led a number of teams at the ION’s past Robotic Lawnmower Competitions. Although Dr. Nattu passed away from a lung illness in 2016, his leadership and true camaraderie during the ASC event serves as the inspiration for this award.

The ASC will award cash prizes to the teams that win each snowfield tournament as part of the competition.

All trophies and prizes will be announced during the Awards Ceremony at the close of the ASC on Saturday afternoon of the competition week.

To qualify for the total dollar prize amounts, a snowplow vehicle must plow at least 50% of the snowfield path during their competition run as scored by the ASC Judges. If less than 50% of the snowfield path is plowed, then the ASC team will only receive 50% of the total prize.
4 Appendix

4.1 Acronyms

The contents of Table 4 provide a list of commonly used acronyms for the ASC, including those used within this rulebook.

<table>
<thead>
<tr>
<th>Acronym</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>ASC</td>
<td>Autonomous Snowplow Competition</td>
</tr>
<tr>
<td>ESS</td>
<td>Emergency Stop System</td>
</tr>
<tr>
<td>FQR</td>
<td>Final Qualification Review</td>
</tr>
<tr>
<td>GNSS</td>
<td>Global Navigation Satellite System</td>
</tr>
<tr>
<td>GPS</td>
<td>Global Positioning System</td>
</tr>
<tr>
<td>ION</td>
<td>Institute of Navigation</td>
</tr>
<tr>
<td>PDR</td>
<td>Preliminary Design Review</td>
</tr>
</tbody>
</table>

4.2 Definitions

For the purposes of this competition, the following terms are defined as follows:

**Guidance**: The determination of the desired path or trajectory of travel from a vehicle’s current position and velocity to a specified destination, including the necessary changes in vehicle velocity or attitude to follow the path.

**Navigation**: The determination at a specific instance in time of a vehicle’s position, velocity, and attitude relative to a known reference frame.

**Control**: The manipulation of control surfaces, thrusters, or motors necessary to track the specific guidance commands, while maintaining vehicle stability, along the trajectory to a specified destination.
4.3 Obstacle Images

Images or diagrams of obstacles used within the ASC are provided. These obstacles include the fixed posts and the moving obstacle. These images are representative of the kind of obstacles that teams should expect, and these can be utilized for design and development of the snowplow vehicle and its navigation, guidance, and control system for obstacle avoidance.

Figure 5. Representative fixed post obstacles.

Figure 6. Representative moving obstacle stop sign.